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# Note on the general monic quartic equation

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**Abstract:** In this paper we present a new approach to solving the general monic quartic equation. Moreover, we show that each quartic equation could be considered as a quasi-reciprocal equation, after a suitable translation of the variable.

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### **1** Introduction and historical data

Let

$$f(x) = x^{4} + ax^{3} + bx^{2} + cx + d \in \mathbb{C}[x].$$

The question for solving the equation

$$f(x) = 0 \tag{1}$$

has a long history. There are known three fundamental ways to solve (1). They are based on Vieta's substitution  $x = z - \frac{a}{4}$ , which transforms (1) into the depressed equation

$$h(z) = z^4 + pz^2 + qz + r = 0,$$
(2)

where the coefficients p, q, r depend on a, b, c, d.

The Italian mathematician Ludovico Ferrari (1522–1565) solved (2) with the help of the method known as Ferrari's method (see [4]). After Ferrari, the French mathematician René

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Descartes (1596–1650) proposed another method for solving (2), using factorisation of h(z) with the help of two quadratic polynomials (see [9] and [7], p. 361). The third way for solving (2) was proposed by the Swiss mathematician Leonhard Euler (1707–1783). His method is a generalization of Hüdde's method for solving the trinomial cubic equation

$$x^3 + px + q = 0$$

(see [7], pp. 358–360).

We shall describe the above three ways for solving (2) in the appendix of this paper.

A general approach to solving (1) and other algebraic equations (using symmetric functions of their roots) was developed by the French mathematician Joseph-Louis Lagrange (1736–1813) (see [7], pp. 363–368, and [5]).

More details about solving (1) are contained in [10] and [11].

The topic for the quartic equation and its solving is still actual (see for example [1-3, 6]). In [8] a review of the known algorithms for solving (1) is made and a universal algorithm that generalizes them is proposed.

# **2** Our approach to solving (1)

An essential difference between our approach to solving (1) and the ways mentioned above is that we keep the term  $y^3$ , which plays a fundamental role. First, we substitute in (1)

$$x = y + \lambda, \tag{3}$$

where  $\lambda \in \mathbb{C}$  is an arbitrary parameter, and we obtain

$$g(y) = y^4 + A(\lambda)y^3 + B(\lambda)y^2 + C(\lambda)y + D(\lambda) = 0$$
(4)

with:

$$D(\lambda) = f(\lambda) = \lambda^4 + a\lambda^3 + b\lambda^2 + c\lambda + d;$$
(5)

$$C(\lambda) = \frac{f'(\lambda)}{1!} = f'(\lambda) = 4\lambda^3 + 3a\lambda^2 + 2b\lambda + c;$$
(6)

$$B(\lambda) = \frac{f''(\lambda)}{2!} = 6\lambda^2 + 3a\lambda + b; \tag{7}$$

$$A(\lambda) = \frac{f''(\lambda)}{3!} = 4\lambda + a.$$
(8)

Let  $\lambda$  satisfy the equation:

$$(4\lambda + a^2)f(\lambda) = (f'(\lambda))^2,$$

which is equivalent to the equation

$$(A(\lambda))^2 D(\lambda) = (C(\lambda))^2.$$
(9)

Using (5), (6), (8), after computation (9) yields the following cubic equation with respect to  $\lambda$ :

$$(a^{3} - 4ab + 8c)\lambda^{3} + (a^{2}b - 4b^{2} + 2ac + 16d)\lambda^{2} + (a^{2}c + 8ad - 4bc)\lambda + a^{2}d - c^{2} = 0.$$
 (10)

Now we shall consider some cases:

1)  $\lambda_0 = -\frac{a}{4}$  is a root with multiplicity 3 of (10).

Hence,  $A(\lambda_0) = 0$  and (9) implies  $C(\lambda_0) = 0$ . Then for  $\lambda = \lambda_0$  (4) yields

$$y^{4} + B(\lambda_{0})y^{2} + D(\lambda_{0}) = 0.$$
(11)

Since (11) is a biquadratic equation, it is trivial to be solved. Let  $y_i$ , i = 1, 2, 3, 4 are all roots of (11). Then, from (3) we obtain that

$$x_i = -\frac{a}{4} + y_i, \ i = 1, 2, 3, 4,$$

are all roots of (1);

- 2) The Equation (10) has a root  $\lambda^*$  different from  $-\frac{a}{4}$ .
  - Then  $A(\lambda^*) \neq 0$ .

Now we consider the following subcases.

2.1) For each root  $\lambda$  of the Equation (10), such that  $\lambda \neq -\frac{a}{4}$ ,  $D(\lambda) = 0$  (in particular,  $D(\lambda^*) = 0$ ).

Then (9) implies  $C(\lambda^*) = 0$  and (4) for  $\lambda = \lambda^*$  yields

$$y^{4} + A(\lambda^{*})y^{3} + B(\lambda^{*})y^{2} = 0.$$
 (12)

The Equation (12) has roots  $y_1 = 0, y_2 = 0$ , while its roots  $y_3$  and  $y_4$  satisfy the quadratic equation

$$y^2 + A(\lambda^*)y + B(\lambda^*) = 0.$$

Then (3) implies that

$$x_i = y_i + \lambda^*, \ i = 1, 2, 3, 4,$$

are all roots of (1).

The main subcase of Case 2) is:

2.2) There exists a root  $\tilde{\lambda}$  of the Equation (10), such that  $\tilde{\lambda} \neq -\frac{a}{4}$  (i.e.,  $A(\tilde{\lambda}) \neq 0$ ) and  $C(\tilde{\lambda}) \neq 0$ .

Then for  $\lambda = \tilde{\lambda}$  we rewrite (9) in the form

$$D(\tilde{\lambda}) = \frac{(C(\lambda))^2}{(A(\tilde{\lambda}))^2}.$$
(13)

Since  $C(\tilde{\lambda}) \neq 0$ , then  $D(\tilde{\lambda}) \neq 0$ . Therefore, y = 0 is not a root of the equation

$$y^{4} + A(\tilde{\lambda})y^{3} + B(\tilde{\lambda})y^{2} + C(\tilde{\lambda})y + D(\tilde{\lambda}) = 0.$$
(14)

This gives us the possibility to divide both sides of (14) by  $y^2$  (like in the case of reciprocal equations of degree 4) and obtain

$$y^{2} + D(\tilde{\lambda})\frac{1}{y^{2}} + A(\tilde{\lambda})\left(y + \frac{C(\lambda)}{A(\tilde{\lambda})}\frac{1}{y}\right) + B(\tilde{\lambda}) = 0.$$
 (15)

We must note that the Equation (14) is not a reciprocal equation, but it is similar, since the method for its solving is almost the same. For this reason we call (14) quasi-reciprocal equation. To solve (15), we set

$$z = y + \frac{C(\lambda)}{A(\tilde{\lambda})} \cdot \frac{1}{y}.$$
(16)

Hence, (16) yields

$$z^{2} = y^{2} + \frac{(C(\tilde{\lambda}))^{2}}{(A(\tilde{\lambda}))^{2}} \cdot \frac{1}{y^{2}} + 2\frac{C(\tilde{\lambda})}{A(\tilde{\lambda})}$$

and from (13) we obtain

$$z^{2} = y^{2} + D(\tilde{\lambda})\frac{1}{y^{2}} + 2\frac{C(\lambda)}{A(\tilde{\lambda})}.$$

Hence,

$$y^2 + D(\tilde{\lambda})\frac{1}{y^2} = z^2 - 2\frac{C(\tilde{\lambda})}{A(\tilde{\lambda})}$$

Thus (15) yields the quadratic equation

$$z^{2} + A(\tilde{\lambda})z + B(\tilde{\lambda}) - 2\frac{C(\lambda)}{A(\tilde{\lambda})} = 0.$$
 (17)

Let the roots of (17) be  $z_i$ , i = 1, 2. Then from (16) we obtain

$$z_i = y + \frac{C(\lambda)}{A(\tilde{\lambda})} \cdot \frac{1}{y}, \ i = 1, 2.$$
(18)

Obviously (18) gives us two quadratic equations for y. Let us denote their roots by  $y_1$ ,  $y_2$ ,  $y_3$  and  $y_4$ . Then from (3) we obtain that

$$x_i = y_i + \tilde{\lambda}, \ i = 1, 2, 3, 4,$$

are all roots of (1).

# **3** Conclusion

Our method for solving (1) shows that for every monic quartic equation there exists a translation of its variable, which turns it into a quasi-reciprocal equation. Moreover, the number of these translations for our method is not greater than 3 (because of (10)).

An open problem is if there exists a similar method for solving algebraic equations of degree  $n \ge 5$ .

# 4 Appendix

#### 4.1 A short description of Ferrari's method for solving (2)

Ferrari started from the identity

$$z^{4} + pz^{2} + qz + r = (u_{\alpha}(z))^{2} - v_{\alpha}(z),$$

where:

$$u_{\alpha}(z) = z^{2} + \frac{p}{2} + \alpha; \ v_{\alpha}(z) = 2\alpha z^{2} - qz + \left(\alpha^{2} + p\alpha - r + \frac{p^{2}}{4}\right)$$

and  $\alpha \in \mathbb{C}$  is an arbitrary parameter. After that Ferrari chose such  $\alpha$  that the discriminant of  $v_{\alpha}(z)$  is 0, i.e.,

$$q^{2} - 4.2\alpha \left( \alpha^{2} + p\alpha - r + \frac{p^{2}}{4} \right) = 0.$$

The above resolvent equation is a qubic equation with respect to  $\alpha$ . Let  $\lambda$  is one of its roots. Then

$$v_{\lambda}(z) = 2\lambda(z-\lambda)^2 = \left(\sqrt{2\lambda}(z-\lambda)\right)^2 =: (w_{\lambda}(z))^2.$$

Therefore,

$$z^{4} + pz^{2} + qz + r = (u_{\lambda}(z))^{2} - v_{\lambda}(z) = (u_{\lambda}(z))^{2} - (w_{\lambda}(z))^{2}.$$

Hence,

$$z^4 + pz^2 + qz + r = (u_{\lambda}(z) + w_{\lambda}(z))(u_{\lambda}(z) - w_{\lambda}(z)).$$

Therefore, (2) is equivalent to the following two quadratic equations:

$$u_{\lambda}(z) + w_{\lambda}(z) = 0; \quad u_{\lambda}(z) - w_{\lambda}(z) = 0.$$

#### **4.2** A short description of Descartes' method for solving (2)

To solve (2), Descartes set

$$z^{4} + pz^{2} + qz + r = (z^{2} + uz + v)(z^{2} - uz + t),$$
(19)

where u, v, t are unknown coefficients. Hence,

$$z^{4} + pz^{2} + qz + r = z^{4} + (t + v - u^{2})z^{2} + (ut - uv)z + vt.$$

Therefore,

$$t + v = p + u^2; \ t - v = \frac{q}{u}; \ vt = r.$$

Hence,

$$t = \frac{1}{2}(p + u^2 + \frac{q}{u}); \tag{20}$$

$$v = \frac{1}{2}(p + u^2 - \frac{q}{u});$$
(21)

$$vt = r.$$

After eliminitation of t and v from the above three equalities, Descartes obtained the resolvent equation

$$u^{6} + 2pu^{4} + (p^{2} - 4r)u^{2} - q^{2} = 0.$$

The last after substituton  $u^2 = y$  yields the cubic equation

$$y^3 + 2py^2 + (p^2 - 4r)y - q^2 = 0.$$

For an arbitrary root y of the above equation the corresponding u is given by  $u = \sqrt{y}$  and then the corresponding t and v are obtained from (20) and (21). For these u, v, t (19) shows that (2) is reduced to the following two quadratic equations:

$$z^{2} + uz + v = 0; \ z^{2} - uz + t = 0.$$

# **4.3** A short description of Euler's method for solving (2)

To solve (2), Euler used Hüdde's substitution (but for three variables):

$$z = u + v + w, \tag{22}$$

where u, v, w are unknown variables. Hence,

$$z^{2} = u^{2} + v^{2} + w^{2} + 2(uv + uw + vw);$$
  

$$z^{4} = (u^{2} + v^{2} + w^{2})^{2} + 4(u^{2} + v^{2} + w^{2})(uv + uw + vw) + 4(u^{2}v^{2} + u^{2}w^{2} + v^{2}w^{2})$$
  

$$+ 8uvw(u + v + w).$$

Eliminating the expression uv + uw + vw from the above two equalities and using (22), Euler obtained

$$z^{4} - 2(u^{2} + v^{2} + w^{2})z^{2} - 8uvwz + (u^{2} + v^{2} + w^{2})^{2} - 4(u^{2}v^{2} + u^{2}w^{2} + v^{2}w^{2}) = 0.$$

Comparing the last equation with (2) Euler received:

$$u^{2} + v^{2} + w^{2} = -\frac{p}{2};$$
  $uvw = -\frac{q}{8};$   $u^{2}v^{2} + u^{2}w^{2} + v^{2}w^{2} = \frac{p^{2} - 4r}{16}.$ 

Hence,

$$u^{2} + v^{2} + w^{2} = -\frac{p}{2};$$
  
$$u^{2}v^{2} + u^{2}w^{2} + v^{2}w^{2} = \frac{p^{2} - 4r}{16};$$
  
$$u^{2}v^{2}w^{2} = \frac{q^{2}}{64}.$$

Obviously, the above three equalities are Vieta's formulae for the cubic (resolvent) equation

$$t^{3} + \frac{p}{2}t^{2} + \frac{p^{2} - 4r}{16}t - \frac{q^{2}}{64} = 0$$

with roots:  $t_1 = u^2$ ,  $t_2 = v^2$ ;  $t_3 = w^2$ .

Thus, using (22), Euler finally obtained that the roots of (2) are given by

$$z = \sqrt{t_1} + \sqrt{t_2} + \sqrt{t_3},$$

where  $\sqrt{t_1}, \sqrt{t_2}, \sqrt{t_3}$  are chosen so that

$$\sqrt{t_1}\sqrt{t_2}\sqrt{t_3} = -\frac{q}{8}.$$

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